# Modbus RTU components for automation in buildings, installations and systems 



C | Logline

## I/O components with Modbus RTU For automation in buildings, installations and systems

Safe and low-cost operation of infrastructures in large as well as small buildings requires that the most important operational functions such as system control, air conditioning, ventilation and lighting are automated. However, this also increases the demands on the functions of the building installation, which can usually be met by conventional technology only at considerable expense. For this reason, building automation increasingly uses serial bus systems that transmit information between sensors and actuators, switches and higher-level control systems.

## Bus systems such as Modbus RTU offer various advantages:

## > easier planning and installation of building functions

> high flexibility in building use, as the functions are freely configurable and can therefore be adjusted and readjusted at any time and as required.

## Compact and intelligent I/O components for decentralised applications

Thanks to their compact design for the top-hat rail (front height of 45 mm ) and the wide variety of models, also in IP65 housing screw and spring clamp technology, METZ CONNECT I/O components are ideally suited for use in decentralised applications. The modules can be used where they are really needed. This considerably reduces the amount of control

cabling required compared to a centralised installation in a switch cabinet. Moreover, the compact mixing ratio of the METZ CONNECT I/O components, which is adapted to the respective application, optimises the number of unused inputs or outputs.

## Minimal cabling required and series connection of the I/O components

 using jumper plugsThe power supply and the bus connection $\rightarrow$ Voltage and bus are fed in and passed on via the contacts on the topside or front side of the I/O components. By plugging in jumper connectors $\rightarrow$ with

jumper plugs, up to $15 \mathrm{I} / \mathrm{O}$ components can be connected to one another quickly and easily and arranged in a row. An end terminal allows transition to a continuing cable.

## Modbus components

Modbus RTU (remote terminal unit) is the most widely used fieldbus in industrial automation worldwide. Here Modbus has developed into a de facto standard, since it is an open communication protocol.

## RS485 interface

The RS485 interface has been developed for fast data transmission over long distances in the field, i.e. directly to sensors (such as our input modules) and actuators (such as our output modules). Thus, it allows for cable lengths of up to 1.2 km

This fieldbus also uses the master-slave method based on the RS485 interface. Our components are Modbus slaves and are queried and controlled by a Modbus master.

## Pictograms key

with screw type terminal blocks
Part numbers end with „70"
Designations contain a "F"
$\qquad$


MR-DI4, MR-DI4-IP, MR-DI4-IP with external display MR-F-DI4

4 inputs - digital

| 1108341319, 1108341319IP |
| :--- |
| D110834131901IP, 110834131970 |



MR-DI10
MR-F-DI10

10 inputs - digital

| 娄 1108311319 |
| :--- |
| - 110831131970 |



MR-DO4, MR-DOA4 MR-F-DO4, MR-F-DOA4

4 outputs - digital (relay)
圊 1108361321, 110836132101 -110836132170, 11083613210170

Suitable for the detection of potential-free switch states of electrical limit switches on ventilation flaps or auxiliary contacts on contactors. Examples are fire dampers or ventilation dampers. The inputs can be connected by means of potential-free switches or contacts as well as voltage inputs. The inputs can be queried via standard registers via a Modbus master. The settings of the module address, baud rate and parity are made via two address switches or via software. The MR-DI4-IP is available in IP65 housing and with external status display.

To detect potential-free switch states, for example electrical end position switches on ventilation dampers or auxiliary contacts of power contactors. Depending on how the jumper J has been set, the inputs can be operated as contact and voltage inputs (J-GND jumper) or with activation to GND (A2, J - + 24 jumper).

Suitable for switching electrical components, such as motors, contactors, lamps, louvers, etc. With strong inductive loads, we recommend protecting the relay contacts additionally with an RC element. The outputs can be switched by means of standard objects via a Modbus master. The module address, the baud rate and the parity are set by means of two address switches on the front. The MR-DOA4 without manual operation (potentiometer) is available to prevent unauthorized switching.
> 10 contact or voltage inputs
> Voltage input $30 \mathrm{VAC} / \mathrm{DC}$
> High signal detection > 7 V AC/DC

Outputs

| Inputs | > 4 potential-free contact inputs | > 10 contact or voltage inputs |
| :---: | :---: | :---: |
|  | > Voltage input 30 V AC/DC | > Voltage input $30 \mathrm{~V} \mathrm{AC/DC}$ |
|  | > Switching threshold > 7 V AC/DC | > High signal detection > 7 V AC/DC |

> 4 changeover contacts
> Switching voltage max. 250 V AC
> Rated current max. 5 A/relay
$>$ Total current of all contact 12 A
>Service life electrical $9 \times 10^{4}$
>Service life mechanical $15 \times 10^{6}$

| Principle diagram | Circuit diagram MR-DI4 and MR-DI4-IP see data sheet |  |  |
| :---: | :---: | :---: | :---: |
| Size | MR-DI4: $35 \times 70 \times 65 \mathrm{~mm}$ MR-DI4-IP: $159 \times 41.5 \times 120 \mathrm{~mm}$ | $35 \times 70 \times 65 \mathrm{~mm}$ | MR-DO4: $35 \times 70 \times 65 \mathrm{~mm}$ MR-DOA4: $35 \times 70 \times 65 \mathrm{~mm}$ |



MR-TO4
MR-F-TO4

4 outputs - digital (triac)

| 圁11083013 |
| :--- |
| 〇1108301370 |



MR-AI8
MR-F-Al8
8 inputs - analog universally configurable


## ㄹ.. 1108371302, 1108351302

- 110837130270, 110835130270


MR-AOP4, MR-AO4 MR-F-AOP4, MR-F-AO4

4 outputs - analog

Description To switch electrical components, such as relays, contactors, HVAC valves, etc. Especially suitable for noiseless and cyclic switching (PDM).

To detect resistances and voltages of, for example, passive and active temperature sensors, electrical vent and mixing valves, valve positions, etc. The following characteristic temperature curves are included in the device: $-50^{\circ} \mathrm{C}$ to $150^{\circ} \mathrm{C}$ : PT100, PT500, PT1000, NI1000-TK5000, NI1000-TK6180, BALCO 500 KTY81-110, KTY81-210, NTC-1k8, NTC-5k, NTC-10k, NTC-20k $-40^{\circ} \mathrm{C}$ to $120^{\circ} \mathrm{C}$ : LM235 $-50^{\circ} \mathrm{C}$ to $110^{\circ} \mathrm{C}$ : NTC-10k CAREL
>Selectable temperature characteristic curve
> Resolution 14 Bit
> Voltage input 0 to 10 V DC
> Resolution 10 mV (0.0 to 100 \%)
> Resistance range 40 Ohm-4 MOhm

It can be used as an encoder for control variables, such as electrical vent and mixing valves, valve positions, etc. The front-side potientiometers of the MR-AOP4 allows switching between automatic and manual mode. The MR-AO4 without manual operation (potentiometer) is available to prevent unauthorized switching.
nputs
$\qquad$
$\qquad$
$\qquad$
> 4 digital triac outputs
> Switchung voltage 24 to 250 V AC
> Rated current $0.5 \mathrm{~A} /$ Triac
Outputs
> Switching current $<30$ s 0.8 A
> Fuses (triacs) 2 A each
> Total current over all outputs max. 2.4 A
$\qquad$
Principle diagram
Size
$35 \times 70 \times 75 \mathrm{~mm}$
> Output voltage 0 to 10 V DC
> Output current 5 mA at 10 V DC
> Resolution 10 mV/Digit

$50 \times 70 \times 65 \mathrm{~mm}$


MR-AIO4/2-IP65

4 inputs - analog configurable
2 outputs - analog

## 11084213IP

The Modbus module in an IP65 housing with 4 individually configurable resistance or voltage inputs and 2 analog outputs was developed for decentralized tasks. The inputs are suitable for measuring resistances and voltages of e.g. passive and active temperature sensors, electrical ventilation and mixing dampers, valve positions, etc. The outputs are suitable as manipulated variable transmitters for e.g. electrical ventilation and mixing dampers, valve positions, etc. The inputs can be universally configured and the outputs set via a Modbus master using standard registers. The module address, bit rate and parity can be set using two rotary switches or via the Software.
> Voltage input 0 to 10 V DC
> Resolution 15 Bit
> Resistance range 40 Ohm to 4 MOhm

| Outputs | > 2 changeover contacts <br> > Switching voltage 250 V AC <br> > Switch-on peak <br> MR-DIO4/2: 80 A/20 ms <br> MR-DIO4/2S: $160 \mathrm{~A} / 20 \mathrm{~ms}$ <br> > Continuous current per relay <br> MR-DIO4/2: 16 A <br> MR-DIO4/2-IP: 10 A <br> > Total current of all contacts <br> MR-DIO4/2: 25 A <br> MR-DIO4/2-IP: 20 A <br> > Service life mechanical: $30 \times 10^{6}$, electrical: $1 \times 10^{5}$ | > 2 changeover contacts <br> > Switching voltage 250 V AC <br> > Switch-on peak: $65 \mathrm{~A} / 20 \mathrm{~ms}$ <br> > Continuous current per relay: 10 A <br> > Total current of all contacts: 11:10 A <br> > Service life <br> mechanical: $10 \times 10^{6}$ <br> electrical: $1 \times 10^{5}$ | >Voltage output $2 \times 0$ to 10 V DC <br> > Output current 5 mA to 10 V DC <br> > Resolution 0,625 m V/Digit <br> > 4 support contacts $15 / 24 \mathrm{~V}$ DC for active sensors |
| :---: | :---: | :---: | :---: |
| Principle diagram |  |  |  |
| Size | MR-DIO4/2: $35 \times 70 \times 65 \mathrm{~mm}$ MR-DIO4/2-IP: $159 \times 41.5 \times 120 \mathrm{~mm}$ | $159 \times 41.5 \times 120 \mathrm{~mm}$ | $159 \times 41.5 \times 120 \mathrm{~mm}$ |



## P/N

$\qquad$

| MR-TP |
| :--- |
| MR-F-TP |
| 6 inputs - digital |
| 2 two-stage relay outputs - digital (relay) |
| D 11083813 |
| D 1108381370 |

Description
Suitable to switch, for example, multilevel pumps and fans or louvers. With strong inductive loads, we recommend protecting the relay contacts additionally with an RC element. The inputs and outputs can be switched and scanned with standard commands. The input contacts 1 to 6 are wired with the C2 contacts on two poles to potential-free switches or contacts. The module has a manual control for the outputs. The module address and the bit rate are set with the two address switches on the front.
$\qquad$

Inputs
$\qquad$
> Output contacts $2 \times \mathrm{NO}$ contact (semiconductor), $2 x$ two-stage (relays)
> Semiconductor realys
Switching voltage $2 \times 40$ V AC/DC
Making/breaking current max. 500 mA Nominal current 100 mA
Outputs > Relays
Switching current $2 \times 250$ V AC
Nominal current 6 A (relays) Service life mechanical $30 \times 10^{6}$ cycles
Service life electrical $9 \times 10^{4}$ cycles
Permissible switching frequency
6 per min. at nominal current
or min.at nominal current

Suitable for counting S0 counter pulses. This allows very good integration of the module into an energy controlling system. In case of a power failure, the last counter readings are saved. The buttons are for counter synchronization. The inputs can be scanned by means of standard registers via a Modbus master. The module address, the baud rate and the parity are set by means of two address switches on the front.

Suitable for detecting currents and voltages of, for example, passive and active temperature sensors, electrical vent and mixing valves, valve positions, etc. The inputs can be scanned by means of standard objects via a Modbus master. The module address, the baud rate and the parity are set by means of two address switches on the front.
MR-SI4
MR-F-SI4
4 S0 inputs


MR-Cl4
MR-F-Cl4
4 Inputs - analog (universally parameterizable)

[^0]$\qquad$

| 音11083913 |
| :--- |
| $\square 1108391370$ |




MR－SM3
MR－F－SM3

3 inputs（230 V）－analog
P／N

| 圕 11084113 |
| :--- |
| D 1108411370 |

The module MR－SM3 is a smart meter component for use in building automation． Current，voltage，power and many other values can be recorded by three 230 volt circuits．Moreover，monitoring functions， such as asymmetry，phase failure，phase sequence，and over and undervoltage are provided．The values can be queried using a Modbus－Master．The module address，bit rate and parity are set via two rotary switches on the front or by software．
$\qquad$
$\longrightarrow$

## $>3 x$ analog

Inputs $\quad>$ Input／voltage $230 \mathrm{~V} \mathrm{AC}-20$ to $+15 \%$
＞Input／voltage range 84 to 265 V AC
＞Input／current 0 to 16 A AC


MR－LD6
MR－F－LD6
6 measuring inputs electrodes（Relay） 2 outputs－digital

## 䍚 11084413 － 1108441370

Suitable for monitoring leakage sensor electrodes or the fill level of liquid containers and switch pumps or magnet valves．The re－ sistance of the conductive liquid is measured when the electrodes are lowered into it．It is also possible to signal a cable break（requires sensor LKS－ZD）．The device can be self－re－ liant or operated via a Modbus－Master．The inputs and outputs can then be switched and scanned via standard registers．The module address，bit rate and parity are set via two rotary switches on the front or by software．
＞Inputs／contacts $1 \ldots 6$ connecting the electrodes
＞Input／contacts C common reference potential
＞ $2 \times$ relay output，normally open contact（SPST－NO）
＞Switching voltage 250 V AC ＞Persistent current 6 A


MR－Multi I／O
11 inputs－digital， 7 inputs－analogue 8 outputs－digital， 2 outputs－analogue 1 S0 current interface
害 11084313

The Modbus module MR－Multi I／O is a compact and quickly installable solution for connecting digital and analog signals from the actuator and sensor level directly to a control unit in the building automation via the Modbus RTU protocol．For various tasks， 29 I／Os are available，some of which can be configured．With strong inductive loads，the relay contacts should also be protected with an RC element．With a Modbus master，the inputs and outputs can be switched on and off and queried via standard registers．The module address，bit rate and parity are set via two rotary switches on the front or using software．
＞ $11 \times$ digital optocoupler，indirect－coupled
＞ $1 \times 50$ current interface
＞ $6 x$ analogue universal input 40 Ohm to $4 \mathrm{MOhm},-0$ to 10 V DC
＞ 1 x analogue 0 to 20 mA

## Outputs


＞ 4 x relay，changeover contact（SPDT）， switching voltage 250 V AC， persistent current 6 A ， button manual control
＞ $4 \times$ PhotoMOS switching voltage 24 V AC／DC 100 mA
＞ 2 x analog 0 to 10 V DC

Principle diagram
$\qquad$

| Module |  |  |
| :---: | :---: | :---: |
|  | NG4 NG4-F | $\begin{aligned} & \text { MR-GW } \\ & \text { MR-F-GW } \end{aligned}$ |
|  | Power supply unit 24 V DC/700mA | Modbus RTU / Modbus TCP Gateway |
| P/N | $\square$ 110561 11056170 | $\square$ 11083001 <br> -1108300170 |
| Description | The power supply NG4 supplies regulated direct voltages for supplying power to the respective devices of the product range I/O components. The device supplies regulated direct voltage 24 V DC at a power of 16 watts. | The MR-Gateway MR-GW enables a bidirectional data exchange between Modbus RTU fieldbus devices and a Modbus TCP master (client). The MR-GW can be operated in two modes. Either as a transparent Gateway in the Modbus RTU over TCP operating mode or as a protocol converter (Modbus TCP operating mode). The MR Gateway can be connected to METZ CONNECT Modbus RTU devices via two 4 -pole connection terminals on the front of the device and a bridging plug. An integrated web server is used for setting parameters, management and monitoring of the two interfaces (Ethernet / RS485). The web interface is also used to update the firmware. The MR Gateway is suitable for decentralised mounting in electrical sub-distributors or in switch cabinets on DIN TH35 rail according to IEC 60715. |
| Inputs |  |  |
| Outputs | > Nominal voltage 110 to 240 V AC, $50 / 60 \mathrm{~Hz}$ <br> > Internal fuse T 1.0 A/250 V soldered fuse <br> > Output power 16 W <br> > Output voltage +24 V DC <br> > Operating voltage display green LED <br> > Output current (max.) 700 mA <br> > As-delivered accuracy $\pm 5 \%$ <br> > Mains failure backup 40 ms | > Ethernet interface <br> Network connection: <br> 1x Ethernet port 10/100 Mbits <br> Protocol: Modbus RTU over TCP <br> (Transparent Gateway), Modbus TCP/IP <br> v1.0b, Telnet, HTTP 1.0 <br> > RS485 interface <br> Protocol: Modbus RTU v1.1b3 <br> Transmission rate: 300 to 115200 Bit/s <br> Bus terminating resistor: <br> 120 Ohm disengageable <br> Galvanic separation: 1.5 kV <br> > Supply <br> Operating voltage 24 V DC $+/-10$ \% (SELV) <br> Power consumption (max.) 50 mA |
| Principle diagram |  |  |
| Size | $50 \times 70 \times 65 \mathrm{~mm}$ | $35 \times 69.3 \times 60 \mathrm{~mm}$ |

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## Modul



Submersible electrode TE2
$\qquad$

Description

One-pole submersible electrode made of stainless steel with protective polypropylene cover. Applications: Electrically conductive liquids, water supply, wells, pumping stations and dry run protection.
To be connected to the level sensor ENW-E12 (P/N 110308xx) and MR-LD6 (P/N 11084413).
Contents of the packaging:
$1 \times$ submersible electrode
$1 \times$ protective cover
$1 \times$ PG gland


Leakage sensor LKS-ZD
$\qquad$ 11080101

The USB to RS485 converter allows
to connect devices with serial UART
interface quickly and easily to USB.
The transparent USB plug includes LEDs to view the Tx and Rx traffic on the cable. The other end of the cable consists of bare, tinned wires.
Combined with our configuration software MR-CT, the Modbus devices of the MR series can be connected and configured directly.
The converter is USB and USB 2.0 full speed compatible and supports a data transfer rate up to 3 Mbps . The required USB-RS485 drivers are available to download for free from http://www.ftdichip.com.


MR-CT Software

Modbus configuration tool
www.metz-connect.com

The software MR-CT is used for the parameterization of Modbus devices and also for searching devices in a Modbus network. It allows the setting of all communication parameters such as baud rate, parity, addresses and temperature characteristics of temperature sensors.

## Application matrix

## Application examples for I/O components

| APPLICATION |
| :--- | :--- | :--- |
| Heating |


| APPLICATION | FUNCTION | FUNCTION IS CARRIED OUT BY ... | APPROPRIATE DEVICE |
| :---: | :---: | :---: | :---: |
| Smoke extraction | Smoke extraction with flap drives | Relay, digital output | MR-DO4 |
|  | Detect flap position | Digital or analog output | MR-DI10, MR-AI8 |
|  | Smoke extraction by fan actuation | Relay, digital output | MR-DO4 |
|  | Unblock light barriers of elevators | Digital input | MR-DI10, MR-DI4 |
| Burglary and access control | People counting | Digital input, counting input | MR-SI4, MR-DI10 |
|  | Collect motion detector data | Digital input | MR-DI10, MR-DI4 |
|  | Monitor window contacts | Digital input | MR-DI10, MR-DI4 |
|  | Collect data of vibrabtion detectors (i.e. window panes) | Digital input | MR-DI10, MR-DI4 |
|  | Collect infrared sensor data | Digital input | MR-DI10, MR-DI4 |
|  | Collect radar sensor data | Digital input | MR-DI10, MR-DI4 |
|  | Trigger the alarm sensor | Relay, digital output | MR-DO4 |
| Energy management | Meter reading (water, gas, current, heat) | Digital input, counting input | MR-SI4 |
|  | Load throw-off | Relay, digital output | MR-DO4 |
|  | Motion sensor (turn the light off) | Digital input | MR-DI10 |
|  | Collect temperature values | Analog input | MR-AI8 |
|  | Allocate energy consumption to cost centers | Counting input | MR-SI4 |
| Room control | see functions from: heating, air conditioning, ventilation, smoke extraction, burglar alarm, access control, energy management, lighting and shading, fire alarm | Digital input |  |
|  |  | SO current interface | MR-Multi I/O, |
|  |  | Analog input | MR-SI4, MR-DO4, <br> MR-AI8, MR-AOP4, |
|  |  | Relay, Photo MOS, digital output |  |
|  |  | Analog output |  |
| leakage and level Monitoring | Recording filling levels | Measuring inputs electrodes | MR-LD6, TE1 |
|  | Recording water leaks/burst pipes | Measuring inputs electrodes | MR-LD6, LKS-ZD |
|  | Switching valves on and off | Relay, digital output | MR-LD6, MR-DO4 |

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